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BRS	1056	(250/359.1 or 250/341.8 or 250/339.11 or 250/559.01).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	554	(162/198 or 162/50).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	668	(342/278 or 342/195).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	98	(356/478).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	2222	(162/198 or 162/50 or 162/263 or 162/dig.10-dig.11 or 162/183 or 162/212 or 162/252 or 162/259 or 162/253 or 162/262 or 162/336 or 162/471 or 162/469).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	39	stationary adj array with sensor	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	7	(stationary adj array with sensor) and paper	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	924	paper adj manufacturing adj process	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	2998	kalman adj filter	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	841	(702/172 or 702/183 or 702/189).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	1302	(702/97 or 702/104 or 702/155-159 or 702/170).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
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BRS	1134	(702/for.134 or 702/for.135 or 702/for.155 or 702/for.164 or 702/for.172).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	1457	(702/for.123-for.124 or 702/for.134 or 702/for.136 or 702/for.141 or 702/for.144-for.148 or 702/for.164 or 702/for.170).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
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BRS	4541	((702/for.123-for.124 or 702/for.134 or 702/for.136 or 702/for.141 or 702/for.144-for.148 or 702/for.164 or 702/for.170).ccls.) or ((702/33 or 702/36 or 702/85 or 702/95 or 702/97 or 702/104 or 702/105 or 702/113 or 702/127 or 702/150 or 702/152 or 702/155 or 702/157-158 or 702/166-167 or 702/170 or 702/190 or 702/197).ccls.)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	63	((702/for.123-for.124 or 702/for.134 or 702/for.136 or 702/for.141 or 702/for.144-for.148 or 702/for.164 or 702/for.170).ccls.) or ((702/33 or 702/36 or 702/85 or 702/95 or 702/97 or 702/104 or 702/105 or 702/113 or 702/127 or 702/150 or 702/152 or 702/155 or 702/157-158 or 702/166-167 or 702/170 or 702/190 or 702/197).ccls.) and (kalman adj filter)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	2	((702/for.123-for.124 or 702/for.134 or 702/for.136 or 702/for.141 or 702/for.144-for.148 or 702/for.164 or 702/for.170).ccls.) or ((702/33 or 702/36 or 702/85 or 702/95 or 702/97 or 702/104 or 702/105 or 702/113 or 702/127 or 702/150 or 702/152 or 702/155 or 702/157-158 or 702/166-167 or 702/170 or 702/190 or 702/197).ccls.) and (kalman adj filter) and convolution	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
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BRS	0	((702/for.123-for.124 or 702/for.134 or 702/for.136 or 702/for.141 or 702/for.144-for.148 or 702/for.164 or 702/for.170).ccls.) or ((702/33 or 702/36 or 702/85 or 702/95 or 702/97 or 702/104 or 702/105 or 702/113 or 702/127 or 702/150 or 702/152 or 702/155 or 702/157-158 or 702/166-167 or 702/170 or 702/190 or 702/197).ccls.) and (kalman adj filter) and convolution and error and sensor	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	118	(700/130 or 700/140).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	201	(708/5 or 708/814).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	227	(73/1.45 or 73/1.49 or 73/1.85 or 73/767).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	730	(250/559.19 or 250/559.4).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	1276	((700/130 or 700/140).ccls.) or ((708/5 or 708/814).ccls.) or ((73/1.45 or 73/1.49 or 73/1.85 or 73/767).ccls.) or ((250/559.19 or 250/559.4).ccls.)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	0	((700/130 or 700/140).ccls.) or ((708/5 or 708/814).ccls.) or ((73/1.45 or 73/1.49 or 73/1.85 or 73/767).ccls.) or ((250/559.19 or 250/559.4).ccls.) and (data adj fusion) and kalman	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
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BRS	6784	array adj sensors	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	0	((700/130 or 700/140).ccls.) or ((708/5 or 708/814).ccls.) or ((73/1.45 or 73/1.49 or 73/1.85 or 73/767).ccls.) or ((250/559.19 or 250/559.4).ccls.) and (data adj fusion) and filter and adaptive	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	48	(array adj sensors) and (kalman adj filter)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	47	(stationary adj sensor) and (scanning adj sensor)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	0	((US-4931982-\$).did.) and sensor	USPAT	10/08/03
BRS	107	(700/129).ccls.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	0	((US-4931982-\$).did.) and detector	USPAT	10/08/03
BRS	0	((US-4931982-\$).did.) and sensor	USPAT	10/08/03
BRS	0	((US-4931982-\$).did.) and stationary	USPAT	10/08/03
BRS	0	((US-4931982-\$).did.) and output) and array	USPAT	10/08/03
BRS	1816	array adj sensor	USPAT	10/08/03
BRS	0	(array adj sensor) and (data adj fusing)	USPAT	10/08/03
BRS	4	(array adj sensor) and (data same fusing)	USPAT	10/08/03
BRS	4	((array adj sensor) and (data same fusing)) and sensor	USPAT	10/08/03
BRS	0	((array adj sensor) and (data same fusing)) and sensor and scanning) and stationary	USPAT	10/08/03
BRS	1	((stationary adj array with sensor) and paper) and synthesiz3	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	1	(paper adj manufacturing adj process) and kalman adj filter	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	2	(kalman adj filter) and (paper adj manufacturing)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	1	(kalman adj filter) and (stationary adj array same sensor)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	7	(kalman adj filter) and (stationary with array same sensor)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	1	((702/for.123-for.124 or 702/for.134 or 702/for.136 or 702/for.141 or 702/for.144-for.148 or 702/for.164 or 702/for.170).ccls.) or ((702/33 or 702/36 or 702/85 or 702/95 or 702/97 or 702/104 or 702/105 or 702/113 or 702/127 or 702/150 or 702/152 or 702/155 or 702/157-158 or 702/166-167 or 702/170 or 702/190 or 702/197).ccls.) and (kalman adj filter) and convolution) and error	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	1	((700/130 or 700/140).ccls.) or ((708/5 or 708/814).ccls.) or ((73/1.45 or 73/1.49 or 73/1.85 or 73/767).ccls.) or ((250/559.19 or 250/559.4).ccls.) and (data adj fusion)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	1	((array adj sensors) and (kalman adj filter)) and scanning near sensor	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	2	((stationary adj sensor) and (scanning adj sensor)) and (kalman adj filter)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03

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BRS	1	((US-4931982-\$).did.	USPAT	10/08/03
BRS	3	((700/129).ccls.) and (kalman adj filter)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	10/08/03
BRS	1	((US-4931982-\$).did.) and scanning	USPAT	10/08/03
BRS	1	((US-4931982-\$).did.) and output	USPAT	10/08/03
BRS	1	((US-4931982-\$).did.) and output	USPAT	10/08/03
BRS	3	((array adj sensor) and (data same fusing)) and sensor) and scanning	USPAT	10/08/03
BRS	0	((US-4931982-\$).did.) and frequency	USPAT	10/08/03
BRS	0	((US-4931982-\$).did.) and speed	USPAT	10/08/03
BRS	0	((US-4931982-\$).did.) and velocity	USPAT	10/08/03
BRS	0	((US-4931982-\$).did.) and odometer	USPAT	10/08/03
BRS	2147	odometer	USPAT	10/08/03
BRS	93	odometer and kalman adj filter	USPAT	10/08/03
BRS	38	(odometer and kalman adj filter) and array	USPAT	10/08/03
BRS	37	((odometer and kalman adj filter) and array) and sensors	USPAT	10/08/03
BRS	32	((odometer and kalman adj filter) and array) and sensors) and cross	USPAT	10/08/03
BRS	21	((odometer and kalman adj filter) and array) and sensors) and cross) and (cross same section)	USPAT	10/08/03
BRS	0	((odometer and kalman adj filter) and array) and sensors) and cross) and (cross same section)) and coordinate) and (least adj mean)	USPAT	10/08/03
BRS	21	((odometer and kalman adj filter) and array) and sensors) and cross) and (cross same section)) and coordinate	USPAT	10/08/03
BRS	0	((US-4931982-\$).did.) and synthetic	USPAT	10/08/03
BRS	376	synthetic and kalman	USPAT	10/08/03
BRS	25	(synthetic and kalman) and (mean adj square)	USPAT	10/08/03